

The K Project

LSE Team

ATAPI Driver

ISO Filesystem

Conclusion

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EPITA

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Introduction

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- ATA (*AT Attachment*) original interface standard for hard drives
- Originally named IDE (Integrated Drive Electronics)
- Replaced by SATA (Serial ATA) in 2003



ATAPI

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- ATA Packet Interface
- Designed to use ATA for other devices than hard disks
- In our case: CD-ROM
- Part of the ATA standard
- **SCSI** commands and responses through the ATA interface



ATA - IBM PC

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- 2 ATA controllers (buses)
- IRQ14 and IRQ15 of slave PIC
- Maximum 2 drives per ATA bus
- Each controller has a set of I/O ports



ATA Registers

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Primary registers:

- 1st controller: 0x1f0
- 2nd controller: 0x170
- Offsets from primary register:
 - +0: Data Register
 - +1: Error Register (R)
 - +1: Features Register (W)
 - +2: Sector Count Register
 - +3: LBA Low Register
 - +4: LBA Mid Register
 - +5: LBA High Register
 - +6: Drive/Head Register
 - +7: Status Register (R)
 - +7: Command Register (W)
- Device Control Register (DCR): 0x3f6 and 0x376



Status Register

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- Bit 0: Error (ERR)
- Bit 1: Index Mark (IDX)
- Bit 2: Data Corrected (CORR)
- Bit 3: Data Transfer Requested (DRQ)
- Bit 4: Seek complete (DSC)
- Bit 5: Device Fault (DF)
- Bit 6: Device Ready (DRDY)
- Bit 7: Busy (BSY)



Discover ATAPI drive

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For each ATA bus:

Send 'Software Reset' to the controller's DCR
 Send 'Disable IRQ' to the controller's DCR
 outb(DCR(port), SOFTWARE_RESET)

outb(DCR(port), DISABLE_IRQ)



Discover ATAPI drive

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for drive in (ATA_PORT_MASTER, ATA_PORT_SLAVE): /* Select current drive */ outb(DRIVE_REG(reg), drive); /* Approx. 4 * inb() */ wait_400ns(); /* Look for ATAPI signature */ sig[0] = inb(SECTOR_COUNT_REG(port)) sig[1] = inb(LBA_LO_REG(port)) sig[2] = inb(LBA_MI_REG(port)) sig[3] = inb(LBA_HI_REG(port)) /* * memcmp(siq, ...) * If it matches: saves (req, drive) */

/* reg == PRIMARY_REG || reg == SECONDARY_REG */



Read block

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Send SCSI packet with 'READ 12' command

• To send a packet to the drive:

busy_wait(); outb(FEATURES_REG(drive), 0); /* No overlap/no DM outb(SECTOR_CNT_REG(drive), 0); /* No queuing

outb(LBA_MI_REG(drive), CDROM_BLK_SIZE); outb(LBA_HI_REG(drive), CDROM_BLK_SIZE >> 8); outb(COMMAND_REG(drive), 0xa0); /* PACKET */

wait_packet_req();



Read block

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- To wait for a packet to be requested:
 - Poll the status register until BSY is cleared and DRQ is set
- Write the SCSI packet to the Data Register
 - One word at a time (you must use outw())
- Read Sector Count Reg while it doesn't return DATA_TRANSMIT (0x2)

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Filesystem Conclusion	<pre>Once the SCSI packet has been sent: Read CDROM_BLK_SIZE word by word: inw(DATA_REGISTER(port))</pre>
	 Read Sector Count Register while it does not return PACKET_COMMAND_COMPLETE (0x3)



Recommanded methodology

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Write 'waiting' helper functions:

```
void busy_wait(u16 drive);
```

```
void wait_device_selection(u16 drive);
```

```
void wait_packet_request(u16 drive);
```

These functions should only be doing inb() calls and status checking.

Recommanded methodology (LSE The K Project LSE Team ATAPI Driver Write functions to discover the ATAPI device: void select_drive(u16 bus, u8 slave); bool is_atapi_drive(u16 bus, u8 slave); void discover_atapi_drive();

(LSE	Recommanded methodology
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Conclusion	Write functions to read data on the drive:
	<pre>int send_packet(struct SCSI_packet *pkt, u16 drive,</pre>
	Feel free to modify the proposed function prototypes.



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- On the ATAPI drive, there will be an ISO 9660 filesystem.
- You should already know how it works.
- The header you had in myreadiso is given.

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Conclusion	<pre>int open(const char *pathname, int flags); ssize_t read(int fd, void *buf, size_t count); off_t seek(int fd, off_t offset, int whence); int close(int fd);</pre>



Open and Close

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Open:

- locate the file and store the infos you need to retrieve it quickly
- register an fd in your fd table

Close:

free the fd

Read and Seek

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Seek:

modify the file offset according to whence Read:

- use the informations you stored in open()
- find the blocks of data to read and copy it
- modify the file offset



Contact

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